

Artificial Neural Networks QUAKEN (ANNS)

Biologically inspired computational model:

- (1) <u>Simple computational units (neurons)</u>.
- (2) <u>Highly interconnected</u> connectionist view
- (3) Vast <u>parallel</u> computation, consider:
 - Human brain has ~10¹¹ neurons
 - Slow computational units, switching time $\sim 10^{-3}$ sec (compared to the computer $>10^{-10}$ sec)
 - Yet, you can recognize a face in $\sim 10^{-1}$ sec
 - This implies only about 100 sequential, computational neuron steps - this seems too low for something as complicated as recognizing a face
 - Parallel processing

ANNs are naturally parallel - each neuron is a self-contained computational unit that depends only on its inputs.





Chap 17 (Alex)

- o A simple, single layered neural
 "network" only has a single neuron.
- However, even this simple neural network is already powerful enough to perform classification tasks.









A perceptron computes the value,

$$y = \operatorname{sgn}\left(b + \sum_{i=1}^{m} w_i x_i\right)$$

Ignoring the activation function sgn and setting m = 1, we obtain,

 $y' = b + w_1 x_1$

But this is the equation of a <u>line</u> with slope *w* and offset *b*.

<u>Observation</u>: For the general case the perceptron computes a <u>hyperplane</u> in order to accomplish its classification task,

$$y' = b + \sum_{i=1}^{m} w_i x_i = b + \vec{w} \cdot \vec{x}$$





In order for the hyperplane to become a classifier we need to find b and $w \Rightarrow$ learning!



```
Let D = \{(\overline{x}_1, y_1), (\overline{x}_2, y_2), \dots, (\overline{x}_n, y_n)\} \subset H \times \{-1, +1\}

\overline{w} \leftarrow \overline{0}

b \leftarrow 0

R \leftarrow \max_{1 \le i \le n} | \overline{x}_i |

\eta \leftarrow 0 < \eta < 1

repeat

for i = 1 to n

if sign(\overline{w} \bullet \overline{x}_i + b) \neq y_i then

\overline{w} \leftarrow \overline{w} + \eta y_i \overline{x}_i

b \leftarrow b + \eta y_i R^2

end if

end for

until no mistakes made in the for-loop

return (\overline{w}, b)
```

Note: learning is very different here compared to decision trees...here we have many passes over the data until the perceptron converges on a solution.



http://lcn.epfl.ch/tutorial/english/apb/html/index.html

R perceptron demo



- The learned information is represented as weights and the bias ⇒ <u>sub-symbolic</u>
 <u>learning</u>
- In order to apply this learned information we need a neural network structure
- The learned information is not directly accessible to us \Rightarrow <u>non-transparent model</u>