



Decision Surfaces & Functions

For some decision surface $g(\bar{x}) = \bar{w} \bullet \bar{x} = b$ in an n -dimensional dot product space \mathbb{R}^n we can always construct the decision function,

$$\hat{f}(\bar{x}) = \begin{cases} +1 & \text{if } g(\bar{x}) - b \geq 0, \\ -1 & \text{if } g(\bar{x}) - b < 0, \end{cases}$$

for all $\bar{x} \in \mathbb{R}^n$. Or in more compact form,

$$\hat{f}(\bar{x}) = \text{sign}(\bar{w} \bullet \bar{x} - b),$$

with $\bar{w}, \bar{x} \in \mathbb{R}^n$, $b \in \mathbb{R}$, and

$$\text{sign}(k) = \begin{cases} +1 & \text{if } k \geq 0, \\ -1 & \text{if } k < 0, \end{cases}$$

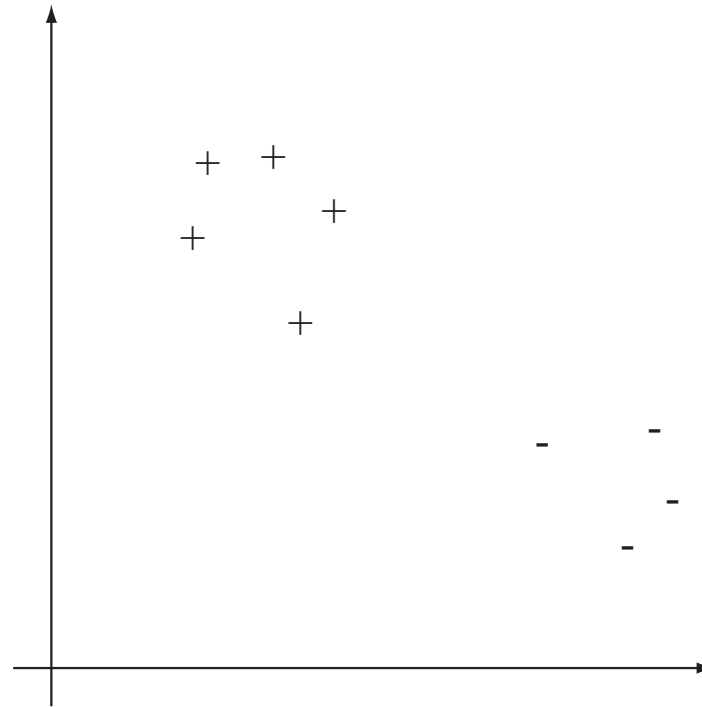
for all $k \in \mathbb{R}$.

A Simple Learning Algorithm

Let's investigate a simple algorithm that actually computes a decision surface for our training set

$$D = \{(\bar{x}_1, y_1), (\bar{x}_2, y_2), \dots, (\bar{x}_l, y_l)\},$$

with $\bar{x}_i \in \mathbb{R}^2$ and $y_i \in \{+1, -1\}$. Here we relax the restriction that the decision surface has to go through the origin but we still assume that D is linearly separable.





A Simple Learning Algorithm

Step 1.

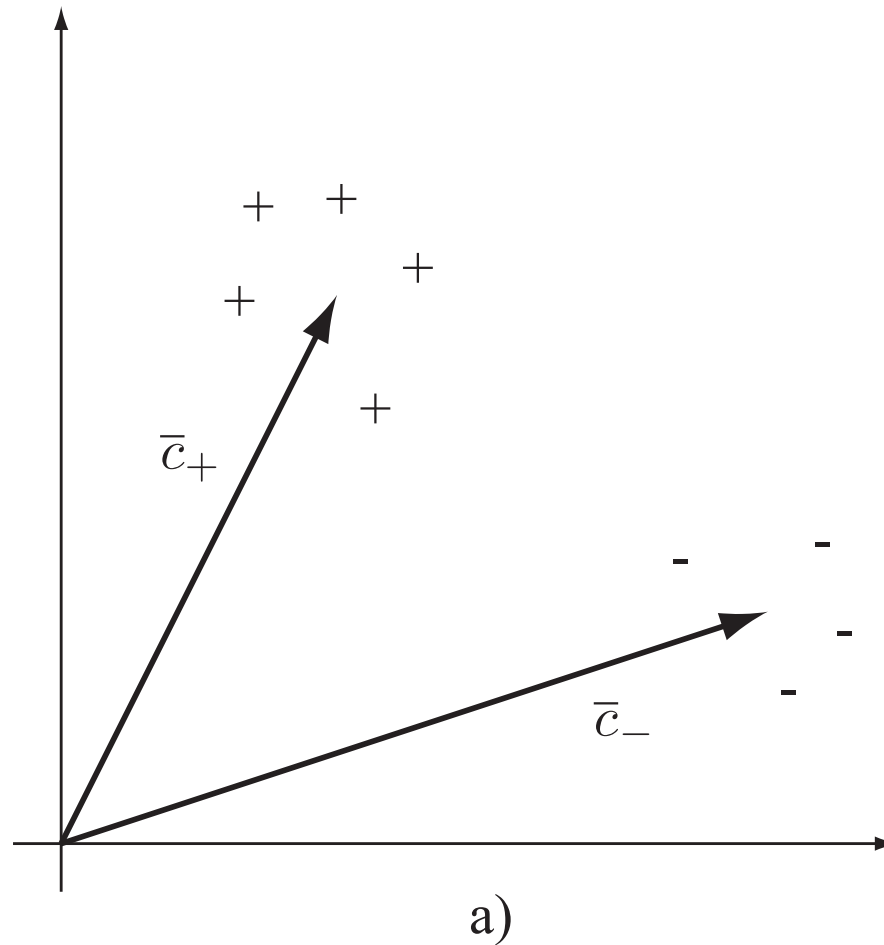
Compute the mean vectors, \bar{c}_+ and \bar{c}_- , for each class, respectively:

$$\begin{aligned}\bar{c}_+ &= \frac{1}{l_+} \sum_{(\bar{x}_i, +1) \in D} \bar{x}_i, \\ \bar{c}_- &= \frac{1}{l_-} \sum_{(\bar{x}_i, -1) \in D} \bar{x}_i,\end{aligned}$$

where

$$\begin{aligned}l_+ &= |\{(\bar{x}, y) \mid (\bar{x}, y) \in D \text{ and } y = +1\}|, \\ l_- &= |\{(\bar{x}, y) \mid (\bar{x}, y) \in D \text{ and } y = -1\}|.\end{aligned}$$

A Simple Learning Algorithm

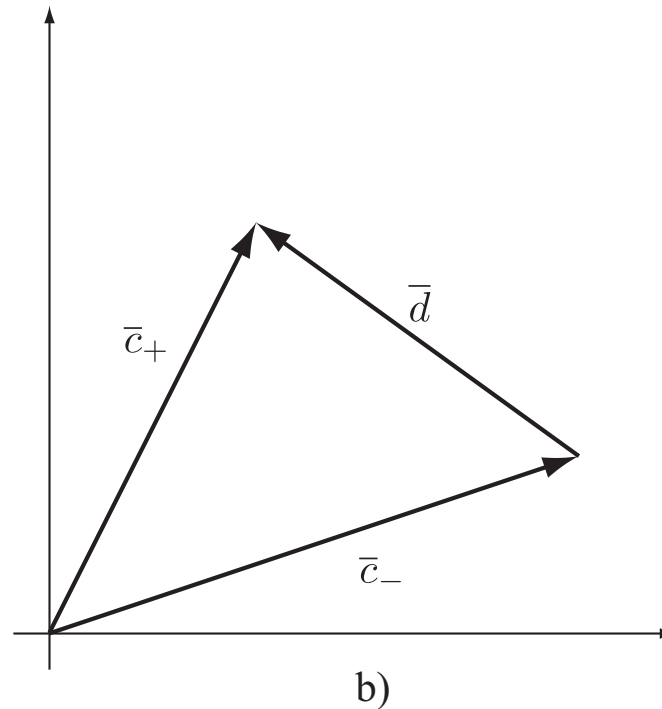


A Simple Learning Algorithm

Step 2.

Next, we construct the vector \bar{d} such that $\bar{c}_+ = \bar{c}_- + \bar{d}$ or,

$$\bar{d} = \bar{c}_+ - \bar{c}_-.$$

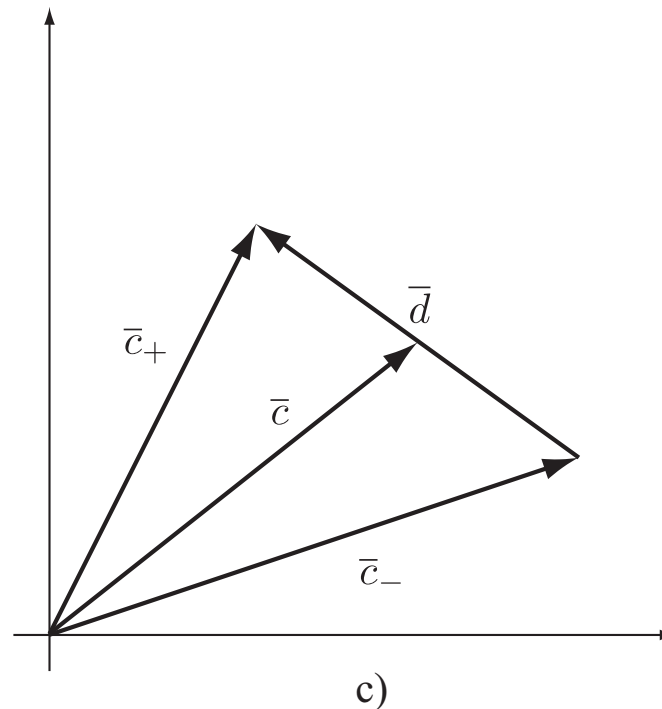


A Simple Learning Algorithm

Step 3.

Compute the midpoint, \bar{c} , between the two means \bar{c}_+ and \bar{c}_- such that

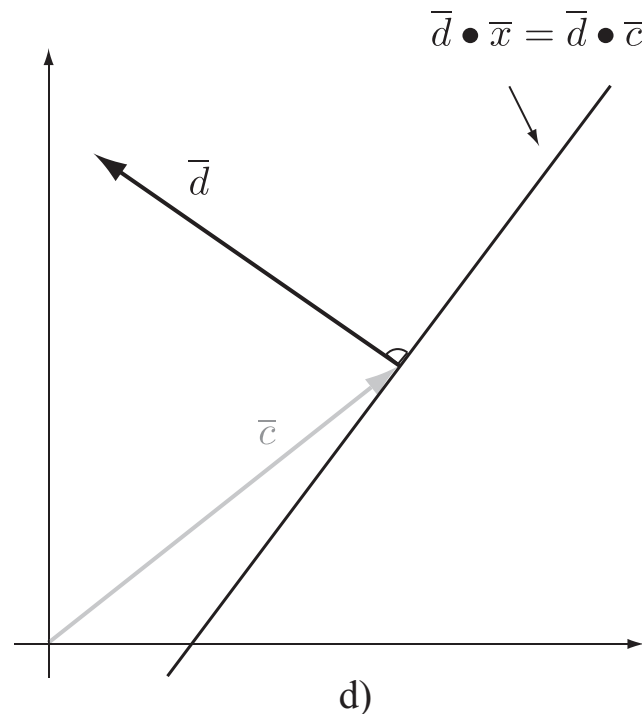
$$\bar{c} = \frac{1}{2}(\bar{c}_+ + \bar{c}_-).$$



A Simple Learning Algorithm

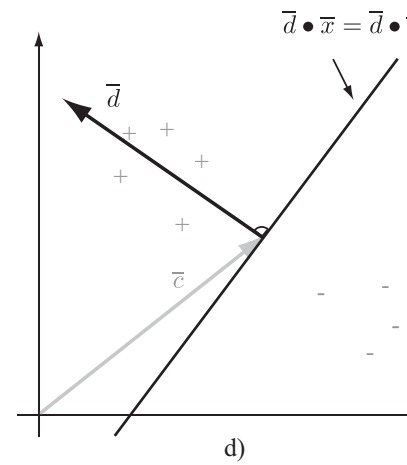
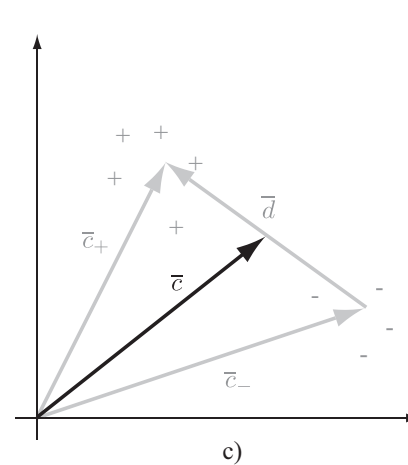
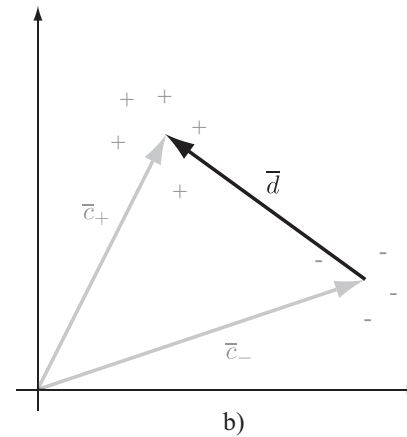
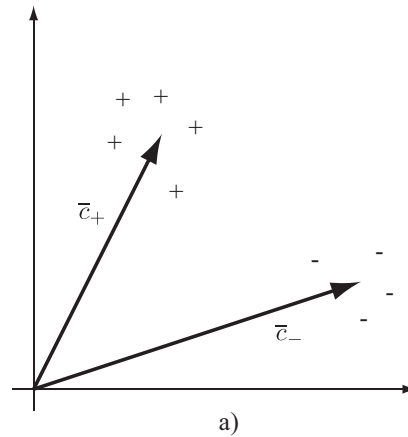
Step 4.

We translate the vector \bar{d} so that it is rooted in the average object \bar{c} and we construct a line perpendicular to \bar{d} through \bar{c} . We can now interpret this line as a decision surface $\bar{w} \bullet \bar{x} = b$ with $\bar{w} = \bar{d}$ and $b = \bar{d} \bullet \bar{c}$, graphically,



A Simple Learning Algorithm

Putting this all together.





A Simple Learning Algorithm

Step 5.

Finally, given our decision surface above we obtain the model,

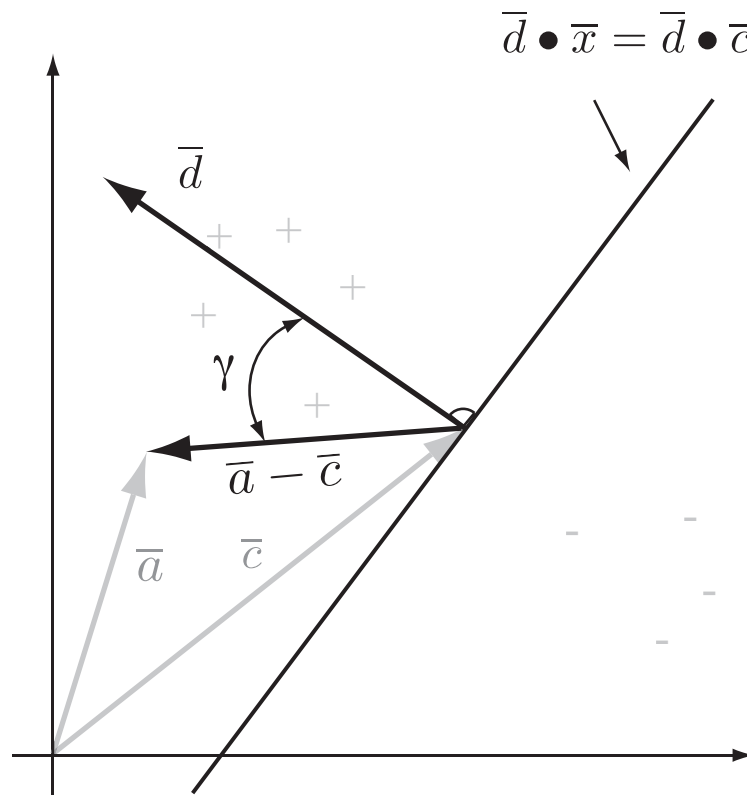
$$\begin{aligned}\hat{f}(\bar{x}) &= \text{sign}(\bar{d} \bullet \bar{x} - \bar{d} \bullet \bar{c}) \\ &= \text{sign} \left((\bar{x} - \bar{c}) \bullet \bar{d} \right) \\ &= \text{sign} \left(|\bar{x} - \bar{c}| |\bar{d}| \cos \gamma \right),\end{aligned}$$

for all $\bar{x} \in \mathbb{R}^2$.

A Simple Learning Algorithm

We can illustrate this with a point \bar{a} ,

$$\hat{f}(\bar{a}) = \text{sign} \left(|\bar{a} - \bar{c}| |\bar{d}| \cos \gamma \right),$$



$$\hat{f}(\bar{a}) = \begin{cases} +1 & \text{if } \gamma \leq 90^\circ \\ -1 & \text{if } \gamma > 90^\circ \end{cases}$$



A Simple Learning Algorithm

We can derive an algebraic form of our model from the definitions of \bar{c} and \bar{d} ,

$$\begin{aligned}\hat{f}(\bar{x}) &= \text{sign} \left((\bar{x} - \bar{c}) \bullet \bar{d} \right) \\ &= \text{sign} \left(\left[\bar{x} - \frac{1}{2}(\bar{c}_+ + \bar{c}_-) \right] \bullet (\bar{c}_+ - \bar{c}_-) \right) .\end{aligned}$$

This shows that the model uses the class means in order to classify unknown points.

A Simple Learning Algorithm

Limitations.

Outliers can distort the orientation of the decision surface which leads to misclassification errors.

