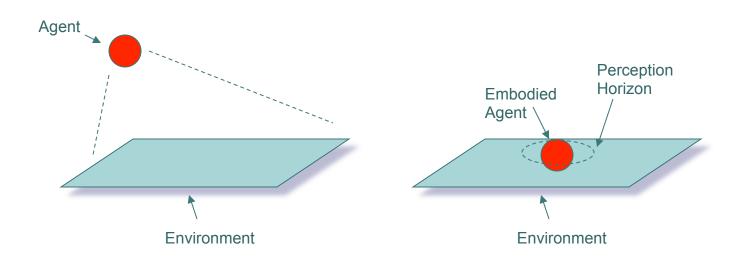


Agents in the Quake Engine

- We will be studying agents in the artificial world of the Quake II game engine
- Quake + Agent = Quagent
- Since the Quake engine is just a software system it would be easy to make supersmart agents that can perceive everything
- Here we limit the agents by the notion of embodiment.



- A software agent could perceive <u>global state information</u>.
- An embodied agent can only perceive information embedded in its <u>immediate local vicinity</u> through its "senses."





Embodiment

- The exact nature of the senses depends on the virtual world the embodied agent inhabits.
- Game engines tend to emulate aspects of the physical world, therefore embodied agents in games tend to have senses that are modeled after our own or other creatures in our physical world:
 - Vision
 - Sense of touch (bumping into things, etc.)
 - Sense of locomotion (e.g., direction, speed)
 - Introspection, well-being
- As a consequence of embodiment the embodied agent has only limited information to base decisions on and limited computational capabilities to make decisions - bounded rationality.



- Embodiment entails having a *body* (albeit simulated for embodied agents in virtual worlds):
 - We need to actively move the body expending energy and plan our route.
 - The body can only move according to the abilities of the embodied agent.
 - The body ages.
 - The body occupies space no two things can exist in the same location in the simulated world.



The Quagent World

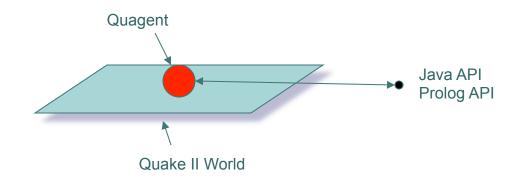
- Worlds are simulated using the Quake II game engine.
 - Simple worlds are provided to you by default:
 - Empty Room
 - Obstacle Room
 - etc.
 - You can build your own world (level design).
 - Or explore other more complicated worlds using your embodied agents.





Quagents

- Quagent = Quake Agent
- A quagent is an embodied agent that inhabits a simulated world.
- The unique property of quagents is that we have access to their "brains."





 The Java and Prolog APIs provide access to the embodied agent body:

- Senses
- State
- Locomotion

• We can write code to control the embodied agents



Quagent Java API

```
class Quagent {
```

```
// spawn a new quagent
public Quagent () throws Exception {...}
public Quagent (String hostName) throws Exception {...}
```

// Actions

public void walk(int distance) throws Exception {...}
public void turn(int angle) throws Exception {...}
public void pickup(String itemName) throws Exception {...}
public Events drop(String itemName) throws Exception {...}

```
// Perception
```

```
public void radius(float radius) throws Exception {...}
public void rays(int no_of_rays) throws Exception {...}
public void cameraon() throws Exception {...}
public void cameraoff() throws Exception {...}
```

```
//Proprioception
```

```
public void where() throws Exception {...}
public void inventory() throws Exception {...}
public void wellbeing() throws Exception {...}
```

```
//Event Retrieval
public Events events() throws Exception {...}
```

```
// Abandon
public void close() throws Exception {...}
```



Quagent Java API

- The Java API is asynchronous.
- The reason: quagents can generate *multiple*, asynchronous messages called events to the brain as a result of a command or the environment.
- These events are captured in the Events object.
- Possible events:
 - OK ([Echo])
 - echos for positive confirmation, as in a submarine movie
 - ERR ([Echo]) [Error Description]
 - can't begin to do command
 - TELL [Event] [Parameters]
 - asynchronous message from quagent: provides information about it's internal state and other parameters



Quagent Java API

```
// connect to a new quagent
Quagent q = new Quagent();
try {
    int dist = (int) (Math.random()*100.0);
    // walk command
    q.walk(dist);
    // get position
    q.where();
    // get wellbeing
    q.wellbeing();
    // get events
    printEvents(q.events());
} catch (QDiedException e) {
    System.out.println("quagent died!");
}
// abandon quagent
q.close();
```



- Walk command, 'walk(distance)'
 - Desire quagent to start walking in current direction. Bot will, at best, start walking in the right direction and silently stop when distance is reached.
 - **GOTCHA:** The quagent is really a bounding box and some graphics that change, often in a cycle, when it is doing something, for example walking. The "realistic" look requires that the quagent move unequal forward distances between the various images that depict its action. Thus your quagents take "different sized steps" during their walk cycle. Therefore, they only approximate the distance in the walk command, and if you are counting steps (ticks) or something to compute your own distances, you can be surprised.
 - Response: OK (do walkby <distance>)
 - Error: ERR <error message>
 - Generates a TELL event to inform you how far the quagent actually walked.
 - TELL STOPPED <actual distance>



Guide Java API Details

- Turn command, 'turn(angle)'
 - Angle is in degrees, + (left turn) or (right turn). Changes current yaw (orientation).
 - Response: OK (do turnby <angle>)
 - Error: ERR <error message>
- Pickup command, 'pickup("tofu")'
 - Immediately picks up one of the named items if quagent is within reach of the item.
 - Response: OK (do pickup <item>)
 - Error occurs if not close enough: ERR <error message>
- Drop command, 'drop("tofu")'
 - Immediately puts down one of the named items in the quagent's inventory.
 - Response: OK (do drop <item>)
 - Error occurs if not in inventory: ERR <error message>



- Radius command, 'radius(100.0)'
 - What items are within the given radius? (There is a system-imposed max-radius).
 - Response: OK (ask radius <radius>) [number of objects] ([object name] [relative position])*
 - here [relative position] is an (x,y,z) three-vector of relative distances.
 - Example: OK (ask radius 100.0) 2 GOLD -20.0 30.0 0 TOFU -320 -100 0
 - Error: ERR <error message>
- Rays command, 'rays(4)'
 - What entities are surrounding quagent in some set of directions. If number is one, ray's direction is in quagent's current direction. The command shoots out rays evenly distributed on a circle around the robot.
 - Response: OK (ask rays <#>) ([ray_number] [object_name] [relative_position])+
 - relative_position is as in the radius command. The "world_spawn" entity is a wall or other game structure.
 - Example: OK (ask rays 2) 1 world_spawn 315.0 277.1 0.0 2 TOFU 200 100 0
 - Error: ERR <error message>



- Cameraon command, 'cameraon()'
 - Normally the terminal shows the view from the (first-person) client. This puts the camera on the quagent.
 - Response: OK (do cameraon)
 - Error: ERR <error message>
- Cameraoff command, 'cameraoff()'
 - Puts camera on client (first-person).
 - Response: OK (do cameraon)
 - Error: ERR <error message>



- Where command, 'where()' 0
 - Where is the quagent, how is it oriented, moving how fast?
 - Response: OK (do getwhere) [world state]
 - where [world state] is a vector of coordinates and a velocity: (world x, world y, world z, roll, pitch, yaw, velocity).
 - Example: OK (do getwhere) 124.5 -366 492 0 0 0 1
 - Error: ERR <error message>
- Inventory command, 'inventory()' 0
 - What is quagent holding?
 - Response: OK (do getinventory) [Inventory]
 - where [Inventory] is (inventory item name)*
 - Example: OK (do getinventory) tofu data
 - Error: ERR <error message>



- Wellbeing command, 'wellbeing()' 0
 - How is guagent doing in its life?
 - Response: OK (do getwellbeing) [well being].
 - Where [well being] is a vector of strings giving the numerical values of (age, health, wealth, wisdom, energy).
 - Example: OK (do getwellbeing) 720 0 0 0 925.6
 - Error: ERR <error message>
 - Generates a 'TELL DYING' event when the quagent dies either of old age or of low energy.
 - The 'TELL DYING' event generates a 'QDiedException' Java exception that you can catch and process.
- Close command, 'close()'
 - Abandons the quagent in the quagent world; the quagent dies immediately (without generating an exception)

DE's are verboten



- IDE's are tool chains that hide a lot of functionality
- In this course we use the raw tools at the OS level:
 - editors (e.g. notepad++)
 - compilers (e.g. javac)
 - loaders (e.g. java)



Running the RandomWalker example guagent program:

- 1) start quake2/empty room by clicking on the appropriate Q2 icon
- 2) open a command shell window
- 3) cd into the directory where the java api and example code is.
- 4) compile all the java code: javac -classpath .;quagent.jar *.java
- 5) run the example: java -classpath .;quagent.jar RandomWalker

If you want to see/edit the code then right click on the RandomWalker Java file and select NotePad++ to edit the code.

Make sure you use the code in folder "Java V3".



Quagent

Template

Application

Programming Tricks -Template

```
// spawn a new quagent in the world
q = new Quagent();
// start a try/catch block and execute the quagent communication
try {
        // do quagent stuff
} catch (QDiedException qe) {
    // the quagent died
    System.out.println("bot died!");
    // ...
} catch (Exception e) {
    // something else bad happened, execute recovery code
    System.out.println(e.getMessage());
    // ...
}
// we are all done with this guagent -- abandon
q.close();
```

QUAKE II

Programming Tricks -Events

- Events are integral to asynchronous programming
- Quagents have a very simple event structure:

```
class Events {
    // constructor
    Events() {...}
    // add an event string to the event object
    public void add(String s) {...}
    // return the number of events in the object
    public int size () {...}
    // return the event at index ix
    public String eventAt(int ix) {...}
}
```

 Events are arrays of strings returned from the game engine,

```
Events e = q.events();
int n = e.size();
String first = e.eventAt(0);
String last = e.eventAt(n-1);
```

• A typical event object might look something like this

```
0: "OK (do walkby <distance>)"
1: "TELL STOPPED <actual distance>"
2: "OK ( ask rays 2 ) 1 world_spawn 315.0 277.1 0.0 2 TOFU
200 100 0"
```



```
public void parseEventCodes(Events events) {
```

// get the event codes

```
// get the individual events from the event object
for (int ix = 0; ix < events.size(); ix++) {</pre>
```

```
String eventString = events.eventAt(ix);
String[] tokens = eventString.split("\\s+");
String eventCode = tokens[0];
String eventVal = tokens[1];
String eventParam = tokens[2];
```

```
// do something useful with the codes
if (eventCode.equals("TELL")) {
    if (eventVal.equals("STOPPED")) {
        System.out.println("Moved: " + eventParam);
    }
} else if (eventCode.equals("OK")) {
    System.out.println("return status OK");
} else if (eventCode.equals("ERR")) {
    System.out.println("return status --> error");
} else {
    continue;
}
```

Parsing Event Codes



• Finding events that share a keyword

```
public Events findEvents(Events events, String kword) {
    Events newEvents = new Events();
    for (int ix = 0; ix < events.size(); ix++) {
        String e = events.eventAt(ix);
        if (e.indexOf(kword) >= 0) {
            newEvents.add(e);
        }
    }
    return newEvents;
}
```



Computing the distance an embodied agent walked

```
public double parseWalkEvent(String eventString) {
    // TELL STOPPED <number>
    String[] tokens = eventString.split("\\s+");
    return Double.parseDouble(tokens[2]);
}
```

QUAKE II

Programming Tricks -Events

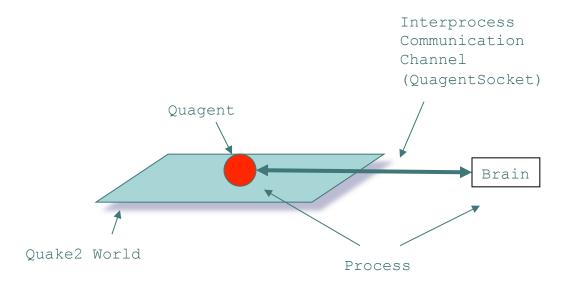
Computing distances with Rays

```
public Double rayDistance(String eventString)
        // NOTE: only works for single ray commands
        // this is what the event looks like:
        // OK (ask rays 1) 1 worldspawn 379.969 54.342 0
        // NOTE: parens are considered white space.
        String[] tokens = eventString.split("[()\\s]+");
        double x = Double.parseDouble(words[6]);
        double y = Double.parseDouble(words[7]);
        double distance = Math.sqrt(x*x + y*y);
        return distance;
```

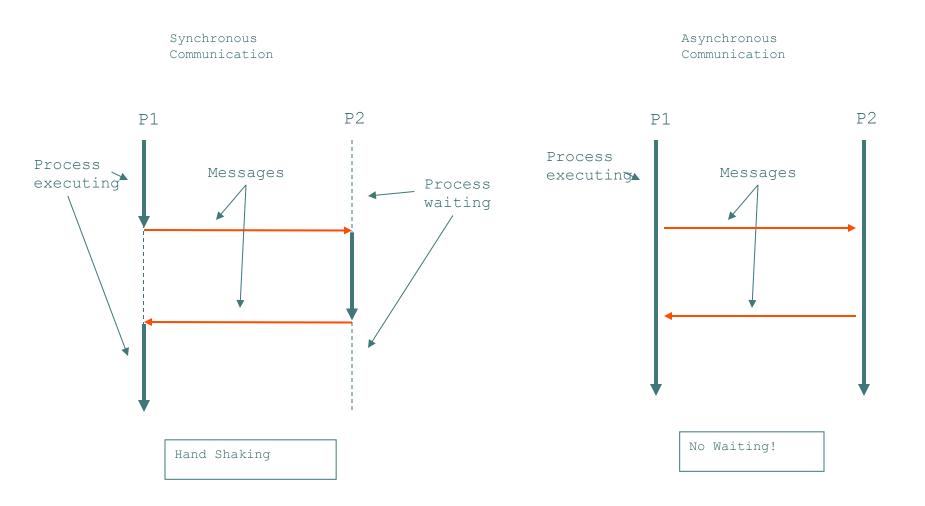


- Why is it so tricky to program Quagents?
 - The body is represented by one process
 - The brain by another process
 - Both processes communicate with each other by passing messages
 - The really tricky part is that these messages are <u>asynchronous</u>!











- Asynchronous communication is more natural in our 0 setting
- Consider the alternatives:
 - the brain stops working while body is walking
 - the body stops walking while the brain is working
- reither of these alternatives is very desirable
- violates one of our central dogmas: be as realistic as possible
- we want both processes to be as unconstrained as possible so that each can perform their respective function as efficiently as possible



Configuring the Quagent World: quagent.config quagent { (TYPE [Botname])? ([variable] [value])* }

[variable] is one of LIFETIME, INITIALWISDOM, INITIALENERGY, INITIALENERGY, INITIALWEALTH, INITIALHEALTH, ENERGYLOWTHRESHOLD, AGEHIGHTHRESHOLD, for which [value] is a string to be interpreted as a number, or it can be this keyword followed by the coordinates: INITIALLOCATION [x] [y] [z]

NOTE:

For each quagent spawned you will need a separate 'quagent' statement in the config file otherwise the quagent will default to mitsu/soldier

```
Available Quagents:
soldier
berserk
gunner
infantry
parasite
Examples:
```

quagent {type soldier initiallocation 128 -236 24.03}
quagent {type parasite lifetime 5000 initialenergy 1000}
quagent {type gunner lifetime 6000 initialenergy 2000}



Configuring the Quagent World: quagent.config	<pre>[object] [x] [y] [z] where [object] is one of the following tofu, data, battery, gold, kryptonite`</pre>
	for which [x] [y] [z] are strings to be interpreted as numbers.
	Examples:
	data -155 256 0 gold 0 0 0



• The Command Shell

- you can kill a process running in the command shell by pressing Cntrl-C
- the TAB key autocompletes a lot of command saving you typing

 a quick tutorial is here: http://www.c3scripts.com/tutorials/msdos/ (link also available from the website)

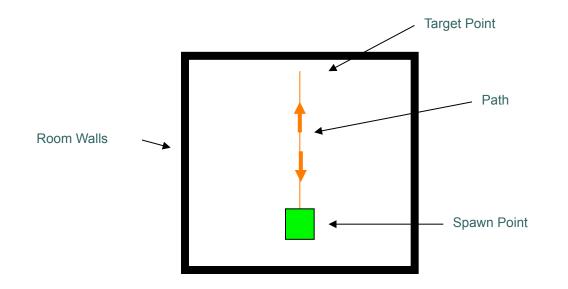
• JDB – the Java Debugger

- javac -g –classpath .;quagent.jar <javafile>
- jdb –classpath .;quagent.jar <classfile>
- stop in <classname>.main (set a break point)
- run execute VM and stop at first break point
- step steps into functions
- next steps over functions
- step up completes a function and returns to the caller
- ont continute normal execution of VM
- print <variable name>
- locals



Programming Exercise #1 – The Walking Guard

Write a quagent program in Java that "walks guard" in the 'Empty Room' world in the following fashion.



Note: You can modify one of the example programs to accomplish this.