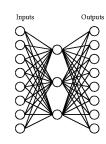


## **Artificial Neural Networks** (ANNs)

Biologically inspired computational model:

- Simple computational units (neurons).
- <u>Highly interconnected</u> connectionist view
- Vast parallel computation, consider:
  - Human brain has ~10<sup>11</sup> neurons
  - Slow computational units, switching time ~10<sup>-3</sup> sec (compared to the computer  $> 10^{-10}$  sec)
  - Yet, you can recognize a face in ~10<sup>-1</sup> sec
  - This implies only about 100 sequential, computational neuron steps - this seems too low for something as complicated as recognizing a face
  - Parallel processing

ANNs are naturally parallel - each neuron is a self-contained computational unit that depends only on its inputs.

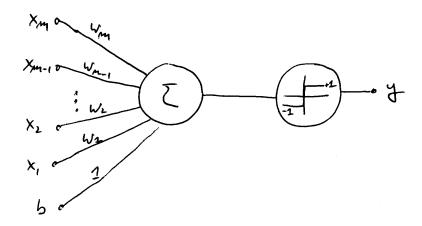




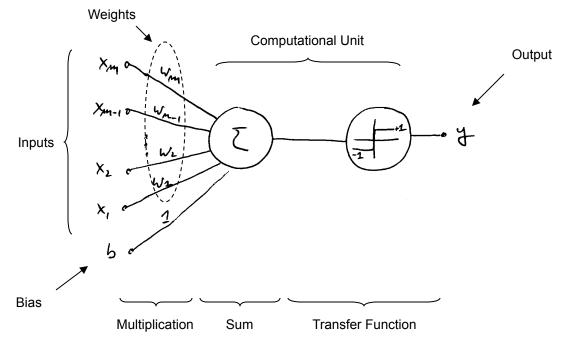
### The Perceptron

Chap 7.4.1 Art Int

- A simple, single layered neural "network" - only has a single neuron.
- However, even this simple neural network is already powerful enough to perform classification tasks.



#### The Architecture



Transfer Function:

$$\operatorname{sgn}(k) = \begin{cases} +1 & \text{if } k \ge 0 \\ -1 & \text{otherwise} \end{cases}$$

Perceptron Computation: 
$$y = \operatorname{sgn}\left(b + \sum_{i=1}^{m} w_i x_i\right)$$

Note: 
$$y \in \{+1,-1\}$$
 Binary Classification

# Computation

A perceptron computes the value,

$$y = \operatorname{sgn}\left(b + \sum_{i=1}^{m} w_i x_i\right)$$

Ignoring the activation function sgn and setting m = 1, we obtain,

$$y' = b + w_1 x_1$$

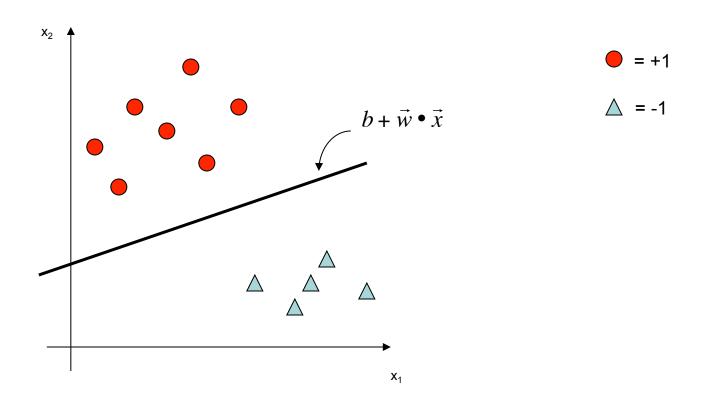
But this is the equation of a <u>line</u> with slope *w* and offset *b*.

Observation: For the general case the perceptron computes a hyperplane in order to accomplish its classification task,

$$y' = b + \sum_{i=1}^{m} w_i x_i = b + \vec{w} \cdot \vec{x}$$



## Classification



In order for the hyperplane to become a classifier we need to find b and  $w \Rightarrow$  learning!

# Learning Algorithm

```
 \begin{array}{l} \operatorname{Let} D = \{(\overline{x}_1, y_1), (\overline{x}_2, y_2), \dots, (\overline{x}_n, y_n)\} \subset H \times \{-1, +1\} \\ \overline{w} \leftarrow \overline{0} \\ b \leftarrow 0 \\ R \leftarrow \max_{1 \leq i \leq n} \mid \overline{x}_i \mid \\ \eta \leftarrow 0 < \eta < 1 \\ \text{repeat} \\ \text{for } i = 1 \text{ to } n \\ \quad \text{if } sign(\overline{w} \bullet \overline{x}_i + b) \neq y_i \text{ then } \\ \quad \overline{w} \leftarrow \overline{w} + \eta y_i \overline{x}_i \\ \quad b \leftarrow b + \eta y_i R^2 \\ \quad \text{end if } \\ \text{end for } \\ \text{until no mistakes made in the for-loop } \\ \text{return } (\overline{w}, b) \\ \end{array}
```

Note: learning is very different here compared to decision trees...here we have many passes over the data until the perceptron converges on a solution.



R perceptron demo



## Observations

- The learned information is represented as weights and the bias ⇒ sub-symbolic learning
- o In order to apply this learned information we need a neural network structure
- The learned information is not directly accessible to us ⇒ non-transparent model